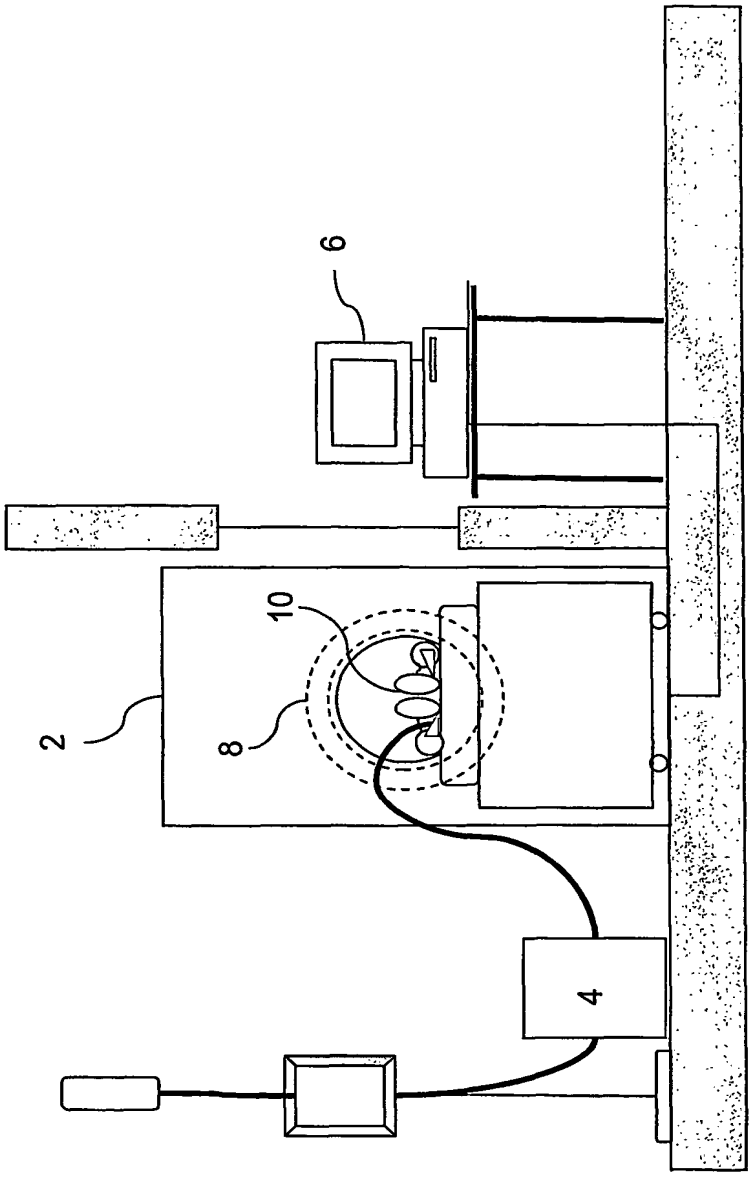

Figure 1

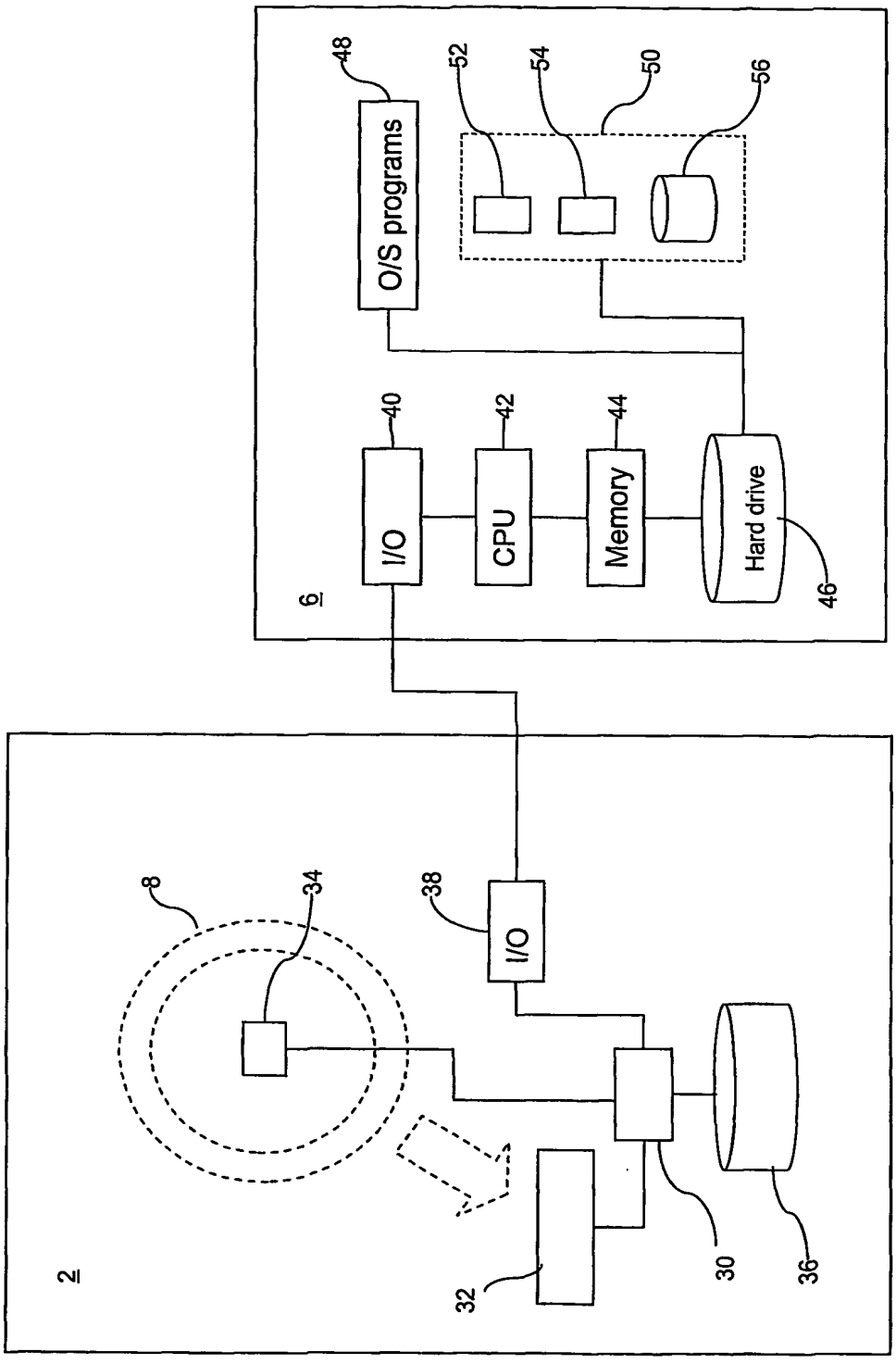
48
52
54
50
56
O/S programs
40
42
44
I/O
CPU
Memory
Hard drive
46
6
8
34
38
I/O
2
32
30
36

Figure 2

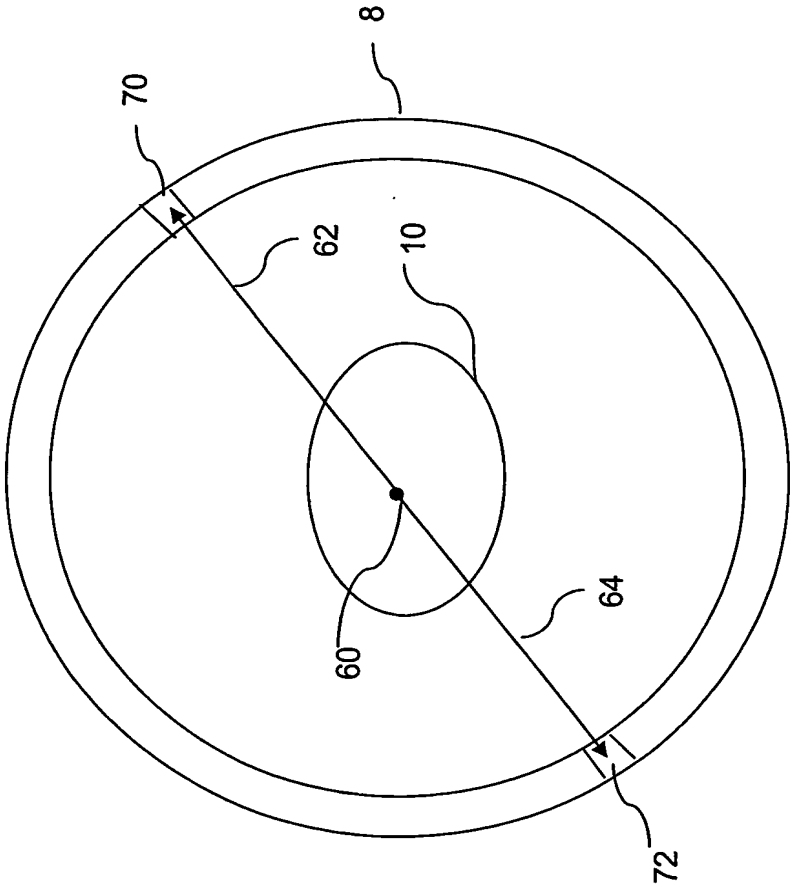

Figure 3

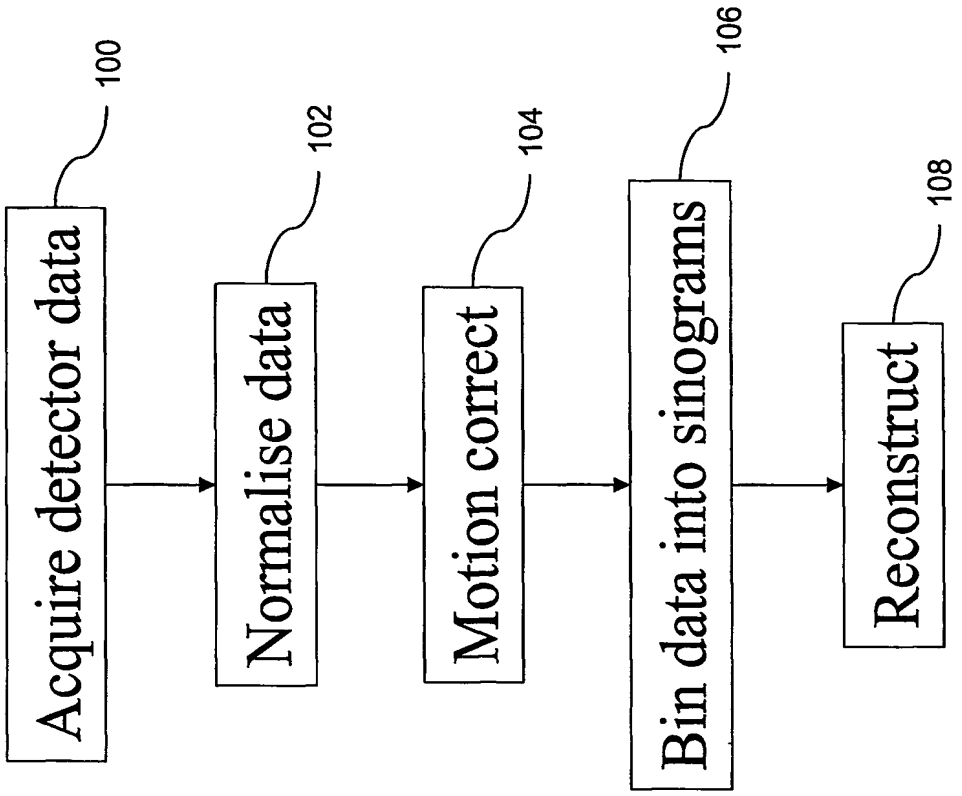
Acquire detector data
100
Normalise data
102
Motion correct
104
Bin data into sinograms
106
Reconstruct
108

Figure 4

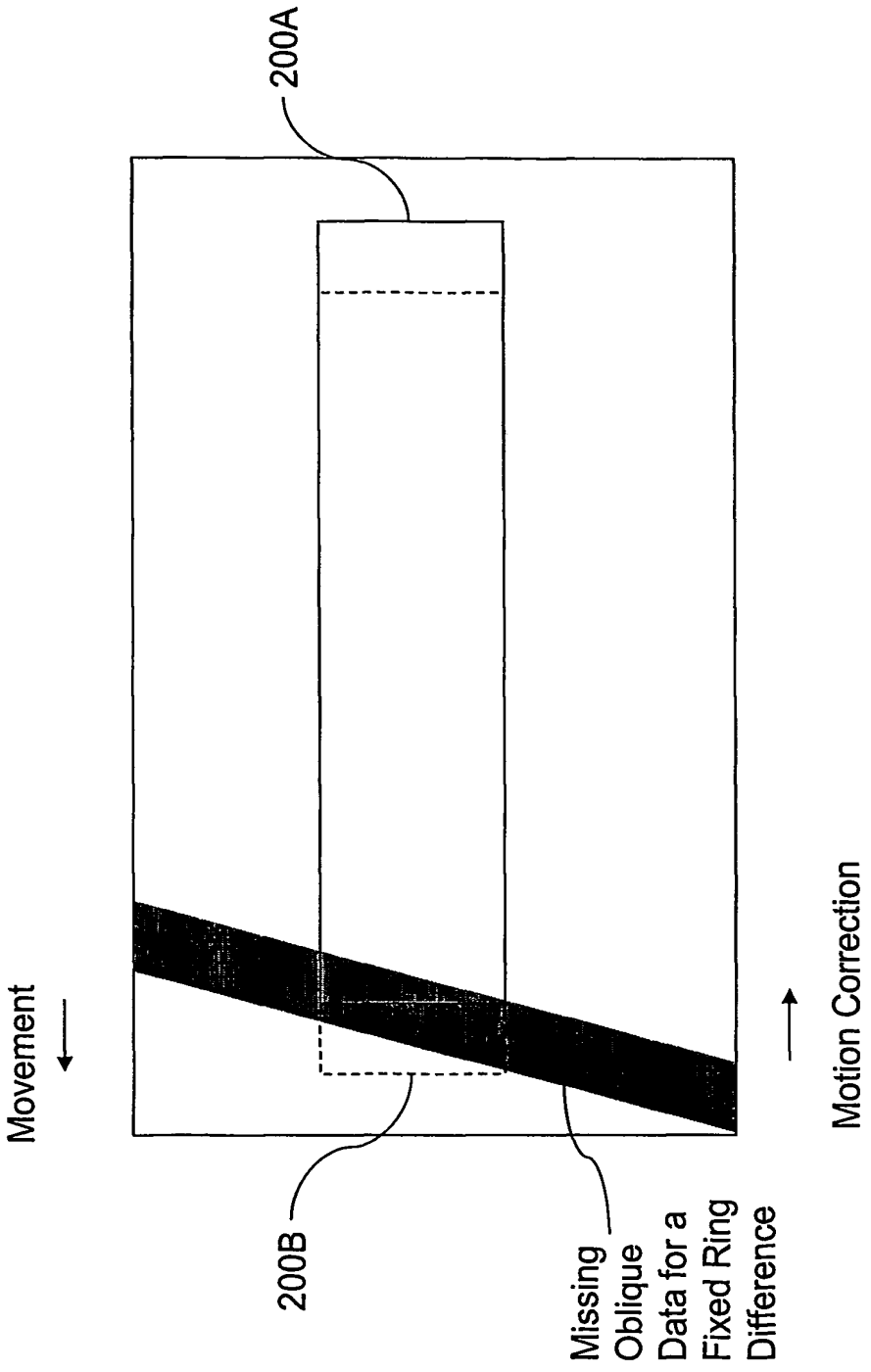
200A
Movement
200B
Missing Oblique Data for a Fixed Ring Difference
Motion Correction

Figure 5

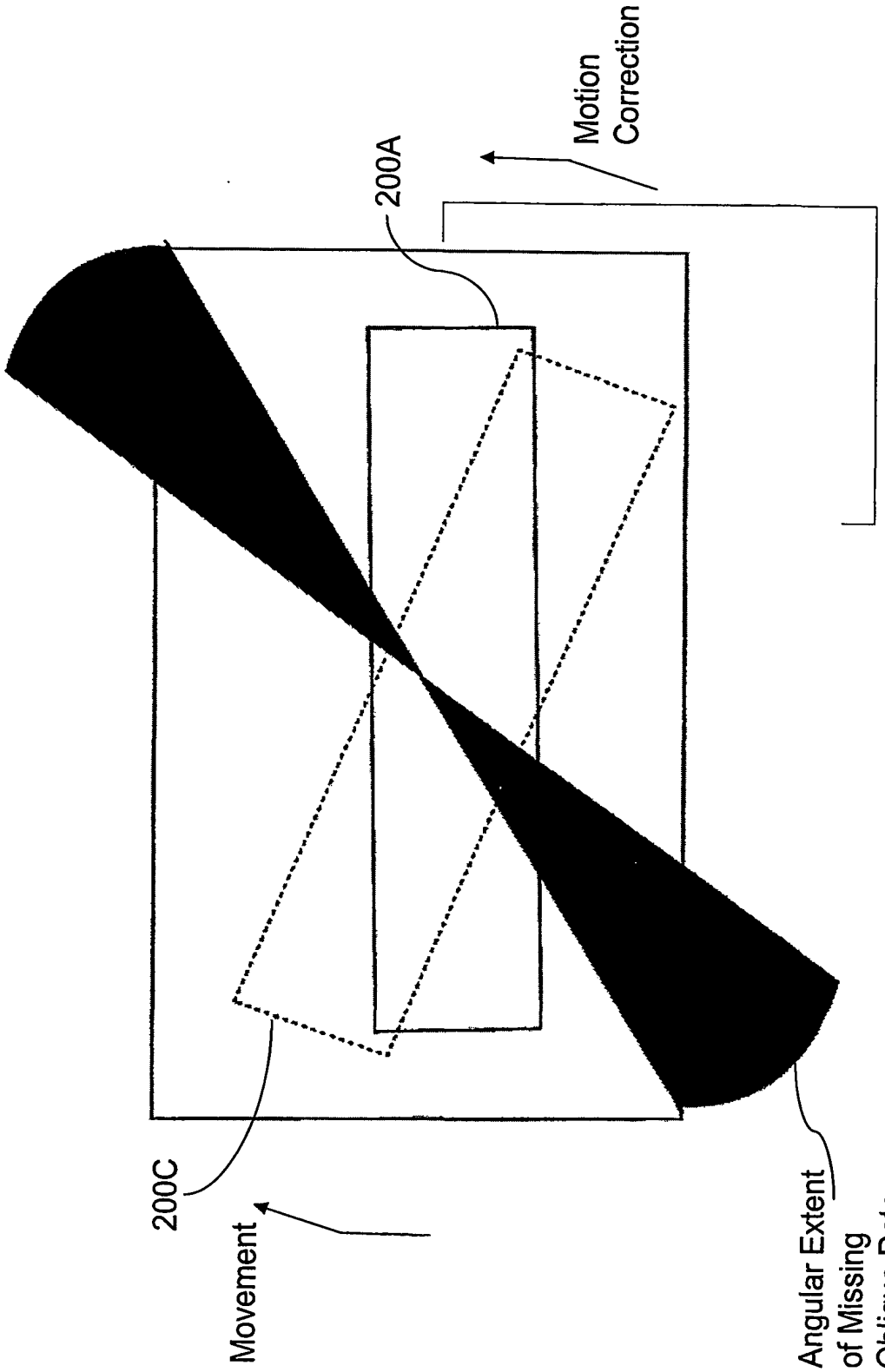
Motion Correction
200A
200C
Movement
Angular Extent of Missing Oblique Data

Figure 6